D OR DGN PACKAGE (TOP VIEW)

2

3

SHUTDOWNE

BYPASS□

IN+□

SLOS208D - JANUARY1998 - REVISED APRIL 2003

Ш V<sub>О</sub>−

 ☐ GND

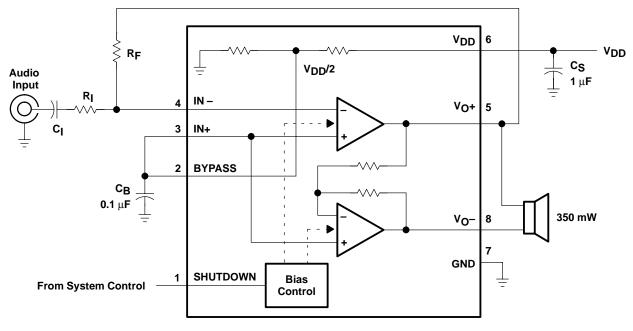
□ V<sub>O</sub>+

 $V_{DD}$ 

- Fully Specified for 3.3-V and 5-V Operation
- Wide Power Supply Compatibility
   2.5 V 5.5 V
- Output Power for  $R_L = 8 \Omega$ 
  - 350 mW at  $V_{DD} = 5$  V, BTL
  - 250 mW at V<sub>DD</sub> = 3.3 V, BTL
- Ultra-Low Quiescent Current in Shutdown Mode . . . 0.15 μA
- Thermal and Short-Circuit Protection
- Surface-Mount Packaging
  - SOIC
  - PowerPAD™ MSOP

#### description

The TPA301 is a bridge-tied load (BTL) audio power amplifier developed especially for low-voltage applications where internal speakers are required. Operating with a 3.3-V supply, the TPA301 can deliver 250-mW of continuous power into a BTL 8- $\Omega$  load at less than 1% THD+N throughout voice band frequencies. Although this device is characterized out to 20 kHz, its operation was optimized for narrower band applications such as cellular communications. The BTL configuration eliminates the need for external coupling capacitors on the output in most applications, which is particularly important for small battery-powered equipment. This device features a shutdown mode for power-sensitive applications with a quiescent current of 0.15  $\mu$ A during shutdown. The TPA301 is available in an 8-pin SOIC surface-mount package and the surface-mount PowerPAD MSOP, which reduces board space by 50% and height by 40%.





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PowerPAD is a trademark of Texas Instruments.



#### **AVAILABLE OPTIONS**

	PACKAGEI	MOOD	
TA	SMALL OUTLINE <sup>†</sup> MSOP <sup>†</sup> (DGN)		MSOP Symbolization
-40°C to 85°C	TPA301D	TPA301DGN	AAA

<sup>†</sup> The D and DGN packages are available taped and reeled. To order a taped and reeled part, add the suffix R to the part number (e.g., TPA301DR).

#### **Terminal Functions**

TERMINA	<b>AL</b>		
NAME	NO.	1/0	DESCRIPTION
BYPASS	2	I	BYPASS is the tap to the voltage divider for internal mid-supply bias. This terminal should be connected to a $0.1$ - $\mu$ F capacitor when used as an audio amplifier.
GND	7		GND is the ground connection.
IN-	4	I	IN – is the inverting input. IN – is typically used as the audio input terminal.
IN+	3	I	IN+ is the noninverting input. IN+ is typically tied to the BYPASS terminal.
SHUTDOWN	1	I	SHUTDOWN places the entire device in shutdown mode when held high ( $I_{DD}$ < 1 $\mu$ A).
$V_{DD}$	6		V <sub>DD</sub> is the supply voltage terminal.
V <sub>O</sub> +	5	0	V <sub>O</sub> + is the positive BTL output.
Vo-	8	0	VO- is the negative BTL output.

#### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)‡

Supply voltage, V <sub>DD</sub>	6 V
Input voltage, V <sub>I</sub>	
Continuous total power dissipation ii	nternally limited (see Dissipation Rating Table)
Operating free-air temperature range, T <sub>A</sub>	–40°C to 85°C
Operating junction temperature range, T <sub>J</sub>	–40°C to 150°C
Storage temperature range, T <sub>stq</sub>	
Lead temperature 1,6 mm (1/16 inch) from case for 10 second	s 260°C

<sup>‡</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### **DISSIPATION RATING TABLE**

PACKAGE	$T_{\mbox{\scriptsize A}} \leq 25^{\circ} \mbox{\scriptsize C}$	DERATING FACTOR	T <sub>A</sub> = 70°C	T <sub>A</sub> = 85°C
D	725 mW	5.8 mW/°C	464 mW	377 mW
DGN	2.14 W§	17.1 mW/°C	1.37 W	1.11 W

<sup>§</sup> Please see the Texas Instruments document, PowerPAD Thermally Enhanced Package Application Report (literature number SLMA002), for more information on the PowerPAD package. The thermal data was measured on a PCB layout based on the information in the section entitled Texas Instruments Recommended Board for PowerPAD on page 33 of the before mentioned document.

#### recommended operating conditions

		MIN	MAX	UNIT
Supply voltage, V <sub>DD</sub>		2.	5 5.5	V
High-level voltage, V <sub>IH</sub>	SHUTDOWN	0.9 V <sub>D[</sub>	)	V
Low-level voltage, V <sub>IL</sub>	SHUTDOWN		0.1 V <sub>DD</sub>	V
Operating free-air temperature, TA		-4	0 85	°C



SLOS208D - JANUARY1998 - REVISED APRIL 2003

# electrical characteristics at specified free-air temperature, $V_{DD}$ = 3.3 V, $T_A$ = 25°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
VOD	Differential output voltage	SHUTDOWN = 0 V, $R_L = 8 \Omega$ , $R_F = 10 k\Omega$		5	20	mV
PSRR	Power supply rejection ratio	V <sub>DD</sub> = 3.2 V to 3.4 V		85		dB
I <sub>DD</sub>	Supply current (see Figure 3)	SHUTDOWN = 0 V, R <sub>F</sub> = 10 k $\Omega$	,	0.7	1.5	mA
I <sub>DD</sub> (SD)	Supply current, shutdown mode (see Figure 4)	SHUTDOWN = $V_{DD}$ , $R_F = 10 \text{ k}\Omega$		0.15	5	μΑ
IIIII	High-level input current	SHUTDOWN, $V_{DD} = 3.3 \text{ V}$ , $V_{I} = 3.3 \text{ V}$			1	μΑ
I <sub>IL</sub>	Low-level input current	SHUTDOWN, $V_{DD} = 3.3 \text{ V}$ , $V_{I} = 0 \text{ V}$			1	μΑ

## operating characteristics, V<sub>DD</sub> = 3.3 V, T<sub>A</sub> = 25°C, R<sub>L</sub> = 8 $\Omega$

	PARAMETER		TEST CONDITIONS		TYP	MAX	UNIT
PO	Output power, see Note 1	THD = 0.5%,	See Figure 9		250		mW
THD + N	Total harmonic distortion plus noise	P <sub>O</sub> = 250 mW, AV = 2 V/V	f = 20 Hz to 4 kHz, See Figure 7		1.3%		
	Maximum output power bandwidth	AV = 2 V/V, See Figure 7	THD = 3%,		10		kHz
B <sub>1</sub>	Unity-gain bandwidth	Open loop,	See Figure 15		1.4		MHz
	Supply ripple rejection ratio	f = 1 kHz, See Figure 2	$C_B = 1 \mu F$ ,		71		dB
V <sub>n</sub>	Noise output voltage	$AV = 1 V/V,$ $R_L = 32 \Omega,$	C <sub>B</sub> = 0.1 μF, See Figure 19		15		μV(rms)

NOTE 1: Output power is measured at the output terminals of the device at f = 1 kHz.

# electrical characteristics at specified free-air temperature, $V_{DD}$ = 5 V, $T_A$ = 25°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
IVODI	Differential output voltage	SHUTDOWN = 0 V, $R_L = 8 \Omega$ , $R_F = 10 k\Omega$		5	20	mV
PSRR	Power supply rejection ratio	V <sub>DD</sub> = 4.9 V to 5.1 V		78		dB
$I_{DD}$	Supply current (see Figure 3)	SHUTDOWN = 0 V, R <sub>F</sub> = 10 k $\Omega$		0.7	1.5	mA
I <sub>DD</sub> (SD)	Supply current, shutdown mode (see Figure 4)	SHUTDOWN = $V_{DD}$ , $R_F = 10 \text{ k}\Omega$	,	0.15	5	μΑ
IIIII	High-level input current	SHUTDOWN, $V_{DD} = 5.5 \text{ V}$ , $V_{I} = V_{DD}$	,		1	μΑ
I <sub>IL</sub>	Low-level input current	SHUTDOWN, $V_{DD} = 5.5 \text{ V}$ , $V_{I} = 0 \text{ V}$			1	μΑ

## operating characteristics, V<sub>DD</sub> = 5 V, T<sub>A</sub> = 25°C, R<sub>L</sub> = 8 $\Omega$

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
PO	Output power	THD = 0.5%,	See Figure 13	·	700		mW
THD + N	Total harmonic distortion plus noise	P <sub>O</sub> = 350 mW, AV = 2 V/V	f = 20 Hz to 4 kHz, See Figure 11		1%		
	Maximum output power bandwidth	AV = 2 V/V, See Figure 11	THD = 2%,		10		kHz
B <sub>1</sub>	Unity-gain bandwidth	Open loop,	See Figure 16	·	1.4		MHz
	Supply ripple rejection ratio	f = 1 kHz, See Figure 2	$C_B = 1 \mu F$ ,		65		dB
V <sub>n</sub>	Noise output voltage	$AV = 1 V/V,$ $R_L = 32 \Omega,$	C <sub>B</sub> = 0.1 μF, See Figure 20		15		μV(rms)



#### PARAMETER MEASUREMENT INFORMATION

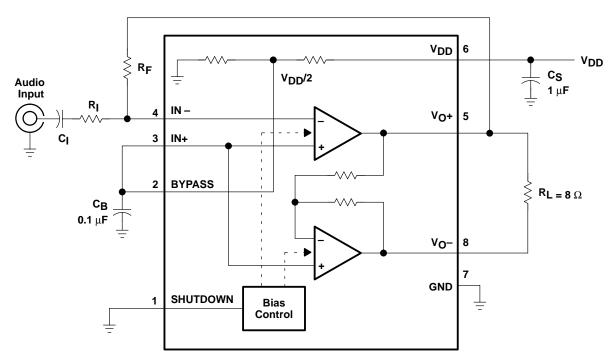


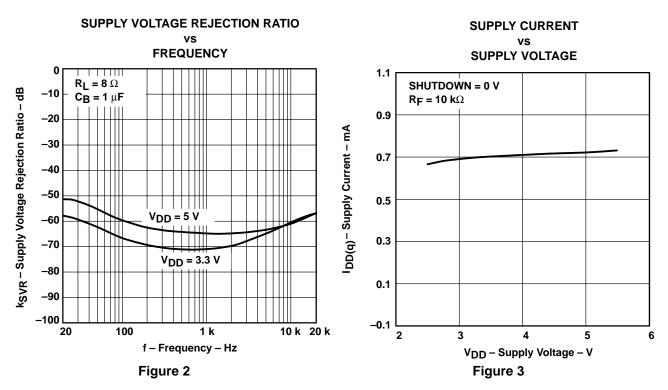
Figure 1. Test Circuit

#### **TYPICAL CHARACTERISTICS**

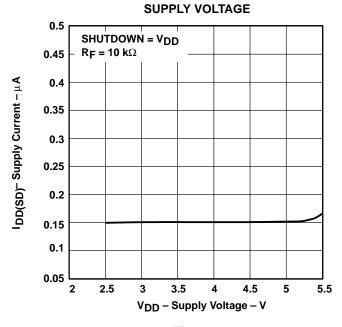
#### **Table of Graphs**

			FIGURE
ksvr	Supply voltage rejection ratio	vs Frequency	2
I <sub>DD</sub>	Supply current	vs Supply voltage	3, 4
5	Outract a second	vs Supply voltage	5
PO	Output power	vs Load resistance	6
THD+N	Total hammania distantian mlua naisa	vs Frequency	7, 8, 11, 12
IHD+N	Total harmonic distortion plus noise	vs Output power	9, 10, 13, 14
	Open loop gain and phase	vs Frequency	15, 16
	Closed loop gain and phase	vs Frequency	17, 18
V <sub>n</sub>	Output noise voltage	vs Frequency	19, 20
$P_{D}$	Power dissipation	vs Output power	21, 22





## SUPPLY CURRENT (SHUTDOWN) vs



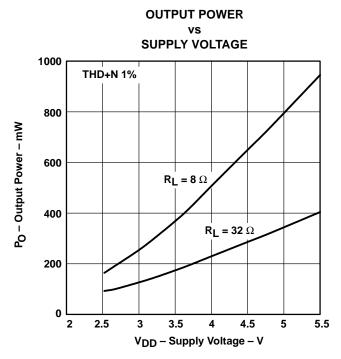


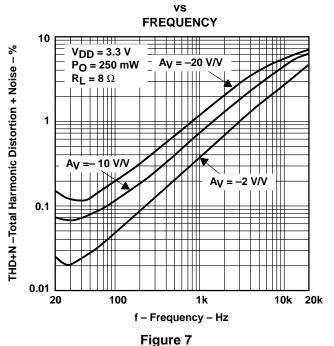
Figure 5

#### **OUTPUT POWER** LOAD RESISTANCE 800 THD+N = 1% 700 600 Po - Output Power - mW $V_{DD} = 5 V$ 500 400 300 $V_{DD} = 3.3 V$ 200 100 0 8 16 32 40 48 56 64 $R_L$ – Load Resistance – $\Omega$

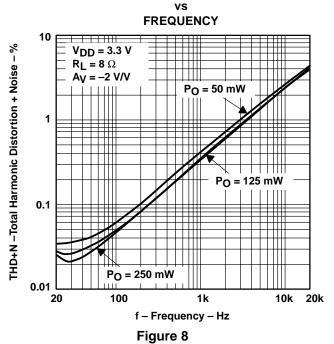


Figure 6

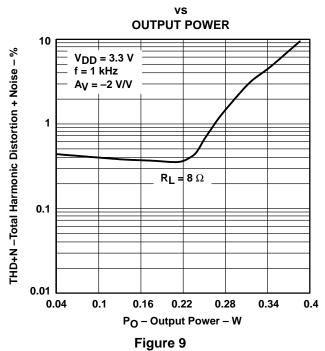
#### TOTAL HARMONIC DISTORTION PLUS NOISE



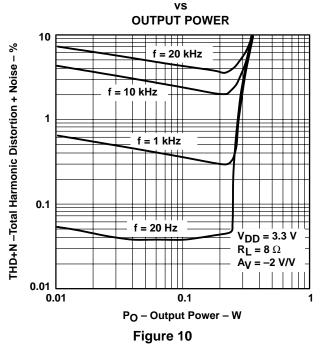
### TOTAL HARMONIC DISTORTION PLUS NOISE



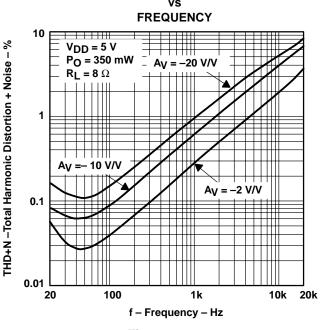
## TOTAL HARMONIC DISTORTION PLUS NOISE



## TOTAL HARMONIC DISTORTION PLUS NOISE

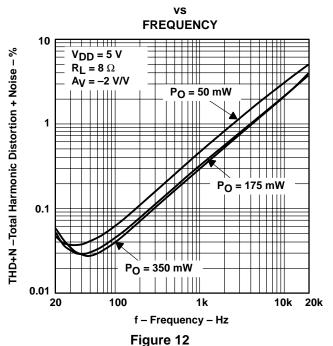


## TOTAL HARMONIC DISTORTION PLUS NOISE

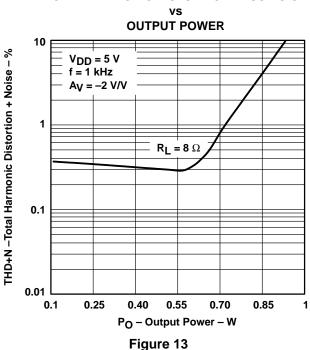


#### Figure 11

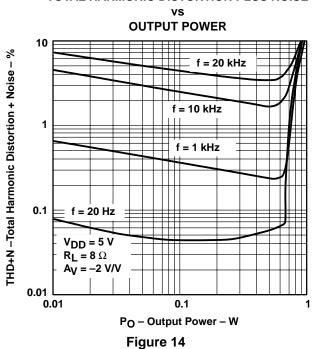
#### TOTAL HARMONIC DISTORTION PLUS NOISE



TOTAL HARMONIC DISTORTION PLUS NOISE



TOTAL HARMONIC DISTORTION PLUS NOISE



TEXAS INSTRUMENTS

## OPEN-LOOP GAIN AND PHASE

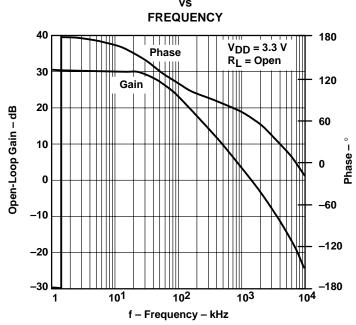


Figure 15

#### **OPEN-LOOP GAIN AND PHASE**

vs **FREQUENCY** 40 180  $V_{DD} = 5 V$ Phase R<sub>L</sub> = Open 30 120 Gain 20 Open-Loop Gain - dB 60 10 0 -60 -10 -120 -20 -30 -180 10<sup>2</sup> 103 10<sup>4</sup> 101 f - Frequency - kHz

Figure 16



#### **CLOSED-LOOP GAIN AND PHASE**

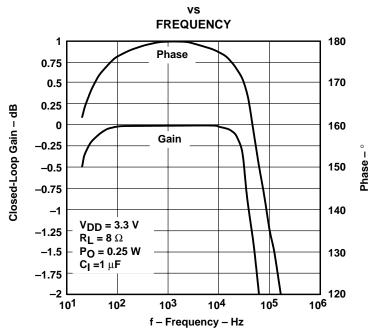


Figure 17

#### **CLOSED-LOOP GAIN AND PHASE**

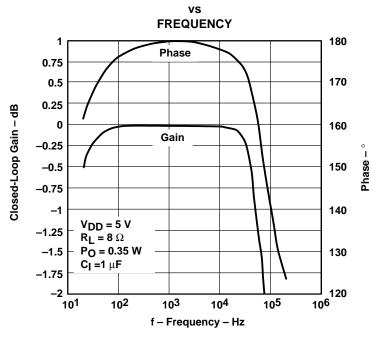
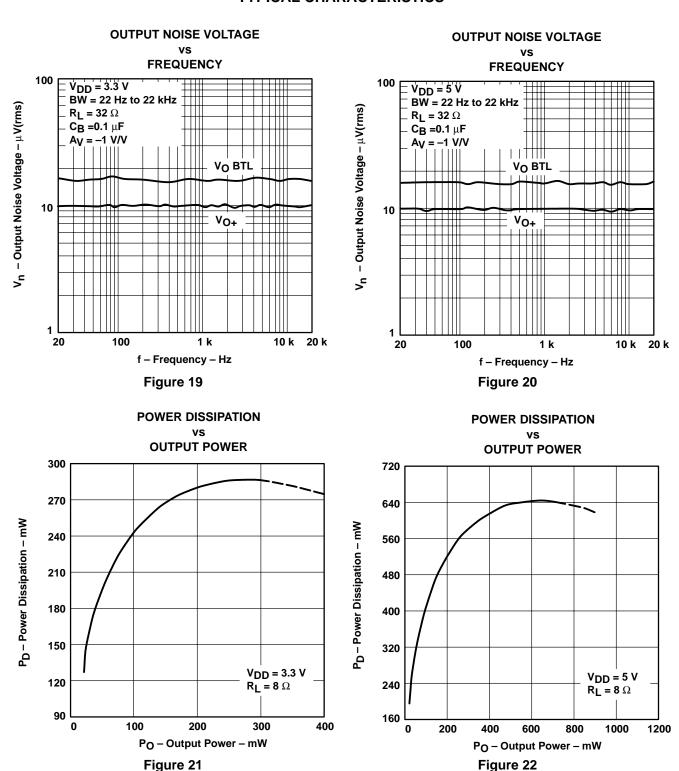


Figure 18





#### bridge-tied load

Figure 23 shows a linear audio power amplifier (APA) in a BTL configuration. The TPA301 BTL amplifier consists of two linear amplifiers driving both ends of the load. There are several potential benefits to this differential drive configuration but power to the load should be initially considered. The differential drive to the speaker means that as one side is slewing up, the other side is slewing down, and vice versa. This in effect doubles the voltage swing on the load as compared to a ground referenced load. Plugging  $2 \times V_{O(PP)}$  into the power equation, where voltage is squared, yields  $4 \times$  the output power from the same supply rail and load impedance (see equation 1).

$$V_{(rms)} = \frac{V_{O(PP)}}{2\sqrt{2}}$$

$$Power = \frac{V_{(rms)}^{2}}{R_{L}}$$
(1)

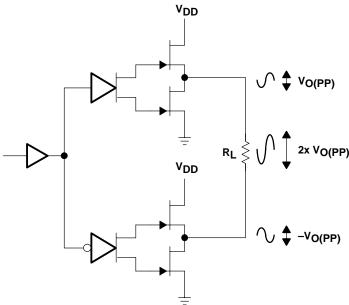


Figure 23. Bridge-Tied Load Configuration

In a typical portable handheld equipment sound channel operating at 3.3 V, bridging raises the power into an 8- $\Omega$  speaker from a single-ended (SE, ground reference) limit of 62.5 mW to 250 mW. In sound power that is a 6-dB improvement — which is loudness that can be heard. In addition to increased power, there are frequency response concerns. Consider the single-supply SE configuration shown in Figure 24. A coupling capacitor is required to block the dc offset voltage from reaching the load. These capacitors can be quite large (approximately 33  $\mu$ F to 1000  $\mu$ F) so they tend to be expensive, heavy, occupy valuable PCB area, and have the additional drawback of limiting low-frequency performance of the system. This frequency limiting effect is due to the high pass filter network created with the speaker impedance and the coupling capacitance and is calculated with equation 2.



#### bridge-tied load versus single-ended mode

$$f_{(corner)} = \frac{1}{2\pi R_L C_C}$$
 (2)

For example, a  $68-\mu\text{F}$  capacitor with an  $8-\Omega$  speaker would attenuate low frequencies below 293 Hz. The BTL configuration cancels the dc offsets, eliminating the need for the blocking capacitors. Low-frequency performance is then limited only by the input network and speaker response. Cost and PCB space are also minimized by eliminating the bulky coupling capacitor.

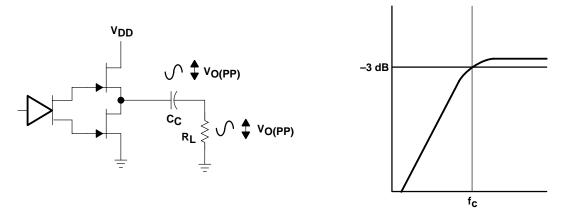


Figure 24. Single-Ended Configuration and Frequency Response

Increasing power to the load does carry a penalty of increased internal power dissipation. The increased dissipation is understandable considering that the BTL configuration produces 4× the output power of a SE configuration. Internal dissipation versus output power is discussed further in the *thermal considerations* section.

#### BTL amplifier efficiency

Linear amplifiers are notoriously inefficient. The primary cause of these inefficiencies is voltage drop across the output stage transistors. There are two components of the internal voltage drop. One is the headroom or dc voltage drop that varies inversely to output power. The second component is due to the sinewave nature of the output. The total voltage drop can be calculated by subtracting the RMS value of the output voltage from  $V_{DD}$ . The internal voltage drop multiplied by the RMS value of the supply current,  $I_{DD}$ rms, determines the internal power dissipation of the amplifier.

An easy-to-use equation to calculate efficiency starts out as being equal to the ratio of power from the power supply to the power delivered to the load. To accurately calculate the RMS values of power in the load and in the amplifier, the current and voltage waveform shapes must first be understood (see Figure 25).

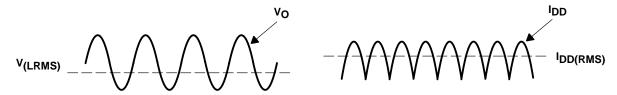


Figure 25. Voltage and Current Waveforms for BTL Amplifiers



#### BTL amplifier efficiency (continued)

Although the voltages and currents for SE and BTL are sinusoidal in the load, currents from the supply are very different between SE and BTL configurations. In an SE application the current waveform is a half-wave rectified shape, whereas in BTL it is a full-wave rectified waveform. This means RMS conversion factors are different. Keep in mind that for most of the waveform both the push and pull transistors are not on at the same time, which supports the fact that each amplifier in the BTL device only draws current from the supply for half the waveform. The following equations are the basis for calculating amplifier efficiency.

$$Efficiency = \frac{P_L}{P_{SUP}}$$
 (3)

where

$$P_{L} = \frac{V_{L} \text{rms}^{2}}{R_{L}} = \frac{V_{p}^{2}}{2R_{L}}$$

$$V_{L} \text{rms} = \frac{V_{p}}{\sqrt{2}}$$

$$P_{SUP} = V_{DD} I_{DD} \text{rms} = \frac{V_{DD} 2V_{p}}{\pi R_{L}}$$

$$2V_{p}$$

$$I_{DD} rms = \frac{2V_{P}}{\pi R_{L}}$$

Efficiency of a BTL Configuration = 
$$\frac{\pi V_P}{2V_{DD}} = \frac{\pi \left(\frac{P_L R_L}{2}\right)^{1/2}}{2V_{DD}}$$
 (4)
Table 1 employs equation 4 to calculate efficiencies for three different output power levels. The efficiency of the

Table 1 employs equation 4 to calculate efficiencies for three different output power levels. The efficiency of the amplifier is quite low for lower power levels and rises sharply as power to the load is increased resulting in a nearly flat internal power dissipation over the normal operating range. The internal dissipation at full output power is less than in the half power range. Calculating the efficiency for a specific system is the key to proper power supply design.

Table 1. Efficiency vs Output Power in 3.3-V 8- $\Omega$  BTL Systems

OUTPUT POWER (W)	EFFICIENCY (%)	PEAK-to-PEAK VOLTAGE (V)	INTERNAL DISSIPATION (W)
0.125	33.6	1.41	0.26
0.25	47.6	2.00	0.29
0.375	58.3	2.45†	0.28

<sup>†</sup> High-peak voltage values cause the THD to increase.

A final point to remember about linear amplifiers (either SE or BTL) is how to manipulate the terms in the efficiency equation to utmost advantage when possible. Note that in equation 4,  $V_{DD}$  is in the denominator. This indicates that as  $V_{DD}$  goes down, efficiency goes up.



#### application schematic

Figure 26 is a schematic diagram of a typical handheld audio application circuit, configured for a gain of -10 V/V.

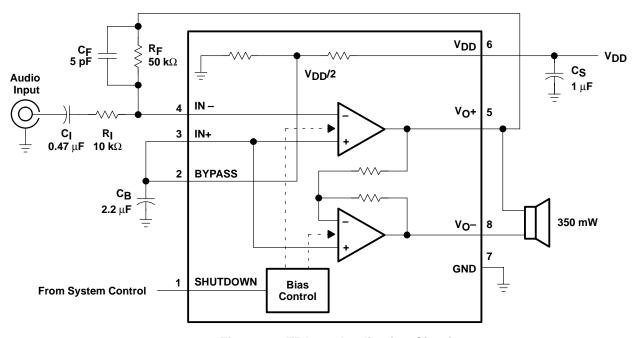


Figure 26. TPA301 Application Circuit

The following sections discuss the selection of the components used in Figure 26.

#### component selection

#### gain setting resistors, RF and RI

The gain for each audio input of the TPA301 is set by resistors R<sub>F</sub> and R<sub>I</sub> according to equation 5 for BTL mode.

BTL Gain = 
$$A_V = -2\left(\frac{R_F}{R_I}\right)$$
 (5)

BTL mode operation brings about the factor 2 in the gain equation due to the inverting amplifier mirroring the voltage swing across the load. Given that the TPA301 is a MOS amplifier, the input impedance is very high, consequently input leakage currents are not generally a concern, although noise in the circuit increases as the value of  $R_{\text{F}}$  increases. In addition, a certain range of  $R_{\text{F}}$  values are required for proper start-up operation of the amplifier. Taken together it is recommended that the effective impedance seen by the inverting node of the amplifier be set between 5  $k\Omega$  and 20  $k\Omega$ . The effective impedance is calculated in equation 6.

Effective Impedance = 
$$\frac{R_F R_I}{R_F + R_I}$$
 (6)

#### component selection (continued)

As an example, consider an input resistance of 10 k $\Omega$  and a feedback resistor of 50 k $\Omega$ . The BTL gain of the amplifier would be -10 V/V, and the effective impedance at the inverting terminal would be 8.3 k $\Omega$ , which is well within the recommended range.

For high performance applications metal film resistors are recommended because they tend to have lower noise levels than carbon resistors. For values of  $R_{\textrm{F}}$  above  $50~\textrm{k}\Omega$  the amplifier tends to become unstable due to a pole formed from  $R_{\textrm{F}}$  and the inherent input capacitance of the MOS input structure. For this reason, a small compensation capacitor,  $C_{\textrm{F}}$ , of approximately 5 pF should be placed in parallel with  $R_{\textrm{F}}$  when  $R_{\textrm{F}}$  is greater than  $50~\textrm{k}\Omega$ . This, in effect, creates a low-pass filter network with the cutoff frequency defined in equation 7.

$$f_{co(lowpass)} = \frac{1}{2\pi R_F C_F}$$
 (7)

For example, if  $R_F$  is 100 k $\Omega$  and  $C_F$  is 5 pF then  $f_{CO}$  is 318 kHz, which is well outside the audio range.

#### input capacitor, CI

In the typical application an input capacitor,  $C_I$ , is required to allow the amplifier to bias the input signal to the proper dc level for optimum operation. In this case,  $C_I$  and  $R_I$  form a high-pass filter with the corner frequency determined in equation 8.

$$f_{co(highpass)} = \frac{1}{2\pi R_{|C|}}$$
 (8)

The value of  $C_I$  is important to consider as it directly affects the bass (low frequency) performance of the circuit. Consider the example where  $R_I$  is 10 k $\Omega$  and the specification calls for a flat bass response down to 40 Hz. Equation 8 is reconfigured as equation 9.

$$C_{I} = \frac{1}{2\pi R_{I} f_{CO}} \tag{9}$$



SLOS208D - JANUARY1998 - REVISED APRIL 2003

#### **APPLICATION INFORMATION**

#### component selection (continued)

In this example,  $C_I$  is 0.40  $\mu F$  so one would likely choose a value in the range of 0.47  $\mu F$  to 1  $\mu F$ . A further consideration for this capacitor is the leakage path from the input source through the input network ( $R_I$ ,  $C_I$ ) and the feedback resistor ( $R_F$ ) to the load. This leakage current creates a dc offset voltage at the input to the amplifier that reduces useful headroom, especially in high gain applications. For this reason a low-leakage tantalum or ceramic capacitor is the best choice. When polarized capacitors are used, the positive side of the capacitor should face the amplifier input in most applications, as the dc level there is held at  $V_{DD}/2$ , which is likely higher than the source dc level. It is important to confirm the capacitor polarity in the application.

#### power supply decoupling, CS

The TPA301 is a high-performance CMOS audio amplifier that requires adequate power supply decoupling to ensure the output total harmonic distortion (THD) is as low as possible. Power supply decoupling also prevents oscillations for long lead lengths between the amplifier and the speaker. The optimum decoupling is achieved by using two capacitors of different types that target different types of noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-series-resistance (ESR) ceramic capacitor, typically 0.1  $\mu$ F, placed as close as possible to the device  $V_{DD}$  lead, works best. For filtering lower-frequency noise signals, a larger aluminum electrolytic capacitor of 10  $\mu$ F or greater placed near the audio power amplifier is recommended.

#### midrail bypass capacitor, CB

The midrail bypass capacitor,  $C_B$ , is the most critical capacitor and serves several important functions. During start-up or recovery from shutdown mode,  $C_B$  determines the rate at which the amplifier starts up. The second function is to reduce noise produced by the power supply caused by coupling into the output drive signal. This noise is from the midrail generation circuit internal to the amplifier, which appears as degraded PSRR and THD + N. The capacitor is fed from a 250-k $\Omega$  source inside the amplifier. To keep the start-up pop as low as possible, the relationship shown in equation 10 should be maintained, which insures the input capacitor is fully charged before the bypass capacitor is fully charged and the amplifier starts up.

$$\frac{10}{\left(C_{\mathsf{B}} \times 250 \,\mathrm{k}\Omega\right)} \le \frac{1}{\left(\mathsf{R}_{\mathsf{F}} + \mathsf{R}_{\mathsf{I}}\right) C_{\mathsf{I}}} \tag{10}$$

As an example, consider a circuit where  $C_B$  is 2.2  $\mu$ F,  $C_I$  is 0.47  $\mu$ F,  $R_F$  is 50  $k\Omega$  and  $R_I$  is 10  $k\Omega$ . Inserting these values into the equation 10 we get:

$$18.2 \le 35.5$$

which satisfies the rule. Bypass capacitor,  $C_B$ , values of 2.2  $\mu F$  to 1  $\mu F$  ceramic or tantalum low-ESR capacitors are recommended for the best THD and noise performance.

#### using low-ESR capacitors

Low-ESR capacitors are recommended throughout this application. A real (as opposed to ideal) capacitor can be modeled simply as a resistor in series with an ideal capacitor. The voltage drop across this resistor minimizes the beneficial effects of the capacitor in the circuit. The lower the equivalent value of this resistance, the more the real capacitor behaves like an ideal capacitor.



#### 5-V versus 3.3-V operation

The TPA301 operates over a supply range of 2.5 V to 5.5 V. This data sheet provides full specifications for 5-V and 3.3-V operation, as these are considered to be the two most common standard voltages. There are no special considerations for 3.3-V versus 5-V operation with respect to supply bypassing, gain setting, or stability. The most important consideration is that of output power. Each amplifier in TPA301 can produce a maximum voltage swing of  $V_{DD} - 1$  V. This means, for 3.3-V operation, clipping starts to occur when  $V_{O(PP)} = 2.3$  V as opposed to  $V_{O(PP)} = 4$  V at 5 V. The reduced voltage swing subsequently reduces maximum output power into an 8- $\Omega$  load before distortion becomes significant.

Operation from 3.3-V supplies, as can be shown from the efficiency formula in equation 4, consumes approximately two-thirds the supply power for a given output-power level than operation from 5-V supplies.

#### headroom and thermal considerations

Linear power amplifiers dissipate a significant amount of heat in the package under normal operating conditions. A typical music CD requires 12 dB to 15 dB of dynamic headroom to pass the loudest portions without distortion as compared with the average power output. From the TPA301 data sheet, one can see that when the TPA301 is operating from a 5-V supply into a  $8-\Omega$  speaker 350 mW peaks are available. Converting watts to dB:

$$P_{dB} = 10 Log P_{W} = 10 Log 3500 \text{ mW} = -4.6 \text{ dB}$$

Subtracting the headroom restriction to obtain the average listening level without distortion yields:

```
-4.6 \text{ dB} - 15 \text{ dB} = -19.6 \text{ dB} \text{ (15 dB headroom)}

-4.6 \text{ dB} - 12 \text{ dB} = -16.6 \text{ dB} \text{ (12 dB headroom)}

-4.6 \text{ dB} - 9 \text{ dB} = -13.6 \text{ dB} \text{ (9 dB headroom)}

-4.6 \text{ dB} - 6 \text{ dB} = -10.6 \text{ dB} \text{ (6 dB headroom)}

-4.6 \text{ dB} - 3 \text{ dB} = -7.6 \text{ dB} \text{ (3 dB headroom)}
```

Converting dB back into watts:

```
P<sub>W</sub> = 10<sup>PdB/10</sup>
= 11 mW (15 dB headroom)
= 22 mW (12 dB headroom)
= 44 mW (9 dB headroom)
= 88 mW (6 dB headroom)
= 175 mW (3 dB headroom)
```



SLOS208D - JANUARY1998 - REVISED APRIL 2003

#### **APPLICATION INFORMATION**

#### headroom and thermal considerations (continued)

This is valuable information to consider when attempting to estimate the heat dissipation requirements for the amplifier system. Comparing the absolute worst case, which is 350 mW of continuous power output with 0 dB of headroom, against 12 dB and 15 dB applications drastically affects maximum ambient temperature ratings for the system. Using the power dissipation curves for a 5-V, 8- $\Omega$  system, the internal dissipation in the TPA301 and maximum ambient temperatures is shown in Table 2.

Table 2. TPA301 Power Rating, 5-V, 8-Ω, BTL

PEAK OUTPUT POWER	AVERAGE OUTPUT POWER	POWER DISSIPATION	MAXIMUM AMBIENT TEMPERATURE
(mW)		(mW)	
350	350 mW	600	46°C
350	175 mW (3 dB)	500	64°C
350	88 mW (6 dB)	380	85°C
350	44 mW (9 dB)	300	98°C
350	22 mW (12 dB)	200	115°C
350	11 mW (15 dB)	180	119°C

Table 2 shows that the TPA301 can be used to its full 350-mW rating without any heat sinking in still air up to 46°C.

#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third—party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Mailing Address:

Texas Instruments Post Office Box 655303 Dallas, Texas 75265

Copyright © 2003, Texas Instruments Incorporated